Complétion Jointe de Matrices

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Matrix completion is ...



- Task: given a partially observed data matrix **X**, predict the unobserved entries
- Large matrices: # rows, # columns $\approx 10^5, 10^6$.
- Very under-determined (often only 1-2% observed)
- Application to recommender systems, system identification, image processing, microarray data, etc.



Motivations: recommendation systems, Netflix prize

• A popular example is the Netflix challenge (2006-2009)



- Dataset: 480K users, 18K movies, 100M ratings
- Only 1.1% of the matrix is filled!



- In general, we cannot infer missing ratings without any other information.
- This problem is under-determined, more unknown than observations.
- Low-rank assumption: fill matrix such that rank is minimum. \rightarrow A few factors explain most of the data.

Completion via rank minimization

minimize_W rank(W) s. t.
$$W_{ij} = \underbrace{X_{ij}}_{\text{observed entries}}, (i, j) \in \underbrace{\Omega}_{\text{sampling set}}$$

Non-convex problem and combinatorially NP-hard!!

Convex formulation of the rank minimization problem

$$\operatorname{rank}(\boldsymbol{X}) = \sum_{i=1}^{\min\dim(\boldsymbol{X})} \mathbb{1}_{(\sigma_i(\boldsymbol{X})>0)} = \|\sigma(\boldsymbol{X})\|_0.$$

Replace ℓ_0 by ℓ_1 [Fazel (2002), Srebro et al. (2005); Candes and Tao (2010); Recht et al. (2010); Negahban and Wainwright (2011); Klopp (2014)]:

$$\|\boldsymbol{X}\|_* = \sum_{i=1}^{\min\dim(\boldsymbol{X})} (\sigma_i(\boldsymbol{X})).$$

Hence temping to consider

Nuclear norm minimization:

$$\mathsf{minimize}_{\boldsymbol{W}} \| \boldsymbol{W} \|_* \; \; \mathsf{s. t. } \; W_{ij} = \underbrace{X_{ij}}_{ij} \; \; , \; (i,j) \in \underbrace{\Omega}_{ij} \; \; .$$

observed entries

sampling set

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This is a convex problem !

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Collective Matrix Completion

Collective matrix completion: motivations

• Data is often obtained from a collection of matrices $\mathcal{X} = (\mathbf{X}^1, \dots, \mathbf{X}^V).$



- It may be beneficial to leverage all the available user data by various sources.
- **Cold-Start** problem: in recommender systems, when a new user has no rating it is impossible to predict his ratings.
- Shared structure among the sources can be useful to get better predictions.

Collective matrix completion: model setup

- Each source view $\boldsymbol{X}^{v} \in \mathbb{R}^{d_{u} \times d_{v}}$ and $D = \sum_{v=1}^{V} d_{v}$.
- We assume that the distribution of for each source X^v depends on the matrix of parameters M^v.
- Model: let B^v_{ij} be independent Bernoulli random variables and independent from X^v_{ii}, with parameter π^v_{ii}.

$$Y_{ij}^{v}=B_{ij}^{v}X_{ij}^{v}.$$

- We can think of the B_{ii}^{v} as masked variables.
- π_{ij}^{v} = probability to observe the (i, j)-th entry of the *v*-th source.



Collective matrix completion: sampling scheme

• We consider general sampling model where we only assume:

Assumption 1: There exists a positive constant $0 s.t. <math>\min_{v \in [V]} \min_{(i,j) \in [d_u] \times [d_v]} \pi_{ij}^v \ge p$.

[Klopp (2015); Klopp et al. (2015)]

- $\pi_{i\bullet}^{\nu} = \sum_{j=1}^{d_{\nu}} \pi_{ij}^{\nu}$ the probability to observe an element from the *i*-th row of \mathbf{X}^{ν} .
- $\pi_{\bullet j}^{v} = \sum_{i=1}^{d_u} \pi_{ij}^{v}$ the probability to observe an element from the *j*-th column of \mathbf{X}^{v} .
- Let $\pi_{i} = \max_{v \in [V]} \pi_{i}^{v}$, $\pi_{i} = \sum_{v=1}^{V} \pi_{i}$, and

$$\max_{(i,j)\in [d_u]\times [d_v]}(\pi_{i\bullet},\pi_{\bullet j})\leq \mu.$$

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Exponential family noise

- Heterogeneous sources: (ratings), (counting: number of clicks) (binomial: like/dislike)
- General framework: natural exponential family

 $X_{ij}^{v}|M_{ij}^{v} \sim h^{v}(X_{ij}^{v})\exp\left(X_{ij}^{v}M_{ij}^{v}-G^{v}(M_{ij}^{v})
ight).$

[Gunasekar et al. (2014); Cao and Xie (2016); Lafond (2015)]

• Many distributions belong to the exponential family: Gaussian, binomial, Poisson, exponential, etc.

Assumption 2: - The distribution of X_{ij}^{ν} has sub-exponential tail. - Strong convexity of the log-partition function G^{ν} .

Exponential family noise: estimation procedure

Given observations *Y* = (*Y*¹,..., *Y^V*), we write the negative log-likelihood as

$$\mathscr{L}_{\mathcal{Y}}(\mathcal{W}) = -\frac{1}{d_u D} \sum_{v \in [V]} \sum_{(i,j) \in [d_u] \times [d_v]} B_{ij}^v (Y_{ij}^v W_{ij}^v - G^v (W_{ij}^v)).$$

• The nuclear norm penalized estimator $\widehat{\mathcal{M}}$ of $\boldsymbol{\mathcal{M}}$ is defined as follows:

$$\widehat{\boldsymbol{\mathcal{M}}} = (\widehat{\boldsymbol{M}}^1, \dots, \widehat{\boldsymbol{M}}^V) = \operatorname*{argmin}_{\|\boldsymbol{\mathcal{W}}\|_{\infty} \leq \gamma} \mathscr{L}_{\boldsymbol{\mathcal{Y}}}(\boldsymbol{\mathcal{W}}) + \lambda \|\boldsymbol{\mathcal{W}}\|_*,$$

• $\lambda > 0$ is a positive regularization parameter that balances the trade-off between model fit and privileging a low-rank solution.

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Theorem [A., Klopp 2018]

Assume that Assumptions 1 and 2 hold and

$$\lambda pprox rac{\sqrt{\mu} + (\log(d_u \lor D))^{3/2}}{d_u D}$$

Then, with high probability, one has

$$\frac{1}{d_u D} \|\widehat{\boldsymbol{\mathcal{M}}} - \boldsymbol{\mathcal{M}}\|_F^2 \lesssim \frac{\mathsf{rank}(\boldsymbol{\mathcal{M}})(\mu + (\log(d_u \vee D))^{3/2})}{p^2 d_u D}$$



Exponential family noise: theoretical guarantee

• Uniform sampling: If $c_1/(d_u d_v) \le \pi_{ij}^v \le c_2/(d_u d_v)$, then

$$rac{1}{d_u D} \| \widehat{\mathcal{M}} - \mathcal{M} \|_F^2 \lesssim rac{\mathrm{rank}(\mathcal{M})}{p(d_u \wedge D)}.$$

- We denote n = ∑_{ν∈[V]} ∑_{(i,j)∈[d_u]×[d_v]} π^v_{ij}, the expected number of observations.
- Sample complexity:

 $n \gtrsim \operatorname{rank}(\mathcal{M})(d_u \lor D).$



Example: 1-bit matrix completion

- 1-bit matrix completion: $\mathcal{Y} \in \{+1, -1\}$ with probability $f(\mathcal{M})$ for some link-function f [Davenport et al. (2014); Klopp et al. (2015); Alquier et al. (2017)]
- Klopp et al. (2015) obtained the rate rank(M)(d ∨ D) log(d ∨ D)/n as the upper bound and rank(M)(d ∨ D)/n as the lower bound for 1-bit matrix completion.

Corollary[A., Klopp 2018]

$$\frac{1}{dD}\|\widehat{\boldsymbol{\mathcal{M}}}-\boldsymbol{\mathcal{M}}\|_F^2\lesssim \frac{\mathrm{rank}(\boldsymbol{\mathcal{M}})(d\vee D)}{n},$$

- **Answer** the important theoretical question: what is the exact minimax rate of convergence for 1-bit matrix completion which was previously known up to a logarithmic factor.
- Sum-norm penalization: $\sum_{v \in [V]} \| M^v \|_*$

- We do not assume any specific model for the observations.
- We consider the risk of estimating X^{ν} with a loss function ℓ^{ν} ,
- We focus on non-negative loss functions that are Lipschitz:

Assumption 3: We assume that the loss function $\ell^{v}(y, \cdot)$ is ρ_{v} -Lipschitz in its second argument: $\ell^{v}(y, x) - \ell^{v}(y, x')| \leq \rho_{v}|x - x'|.$

Examples: hinge loss with ℓ^v(y, y') = max(0, 1 − yy'), logistic loss with ℓ^v(y, y') = log(1 + exp(−yy')), etc.



Distribution-free setting: estimation procedure

• Goodness-of-fit term:

$$R_{\mathcal{Y}}(\mathcal{W}) = \frac{1}{d_u D} \sum_{v \in [V]} \sum_{(i,j) \in [d_u] \times [d_v]} B_{ij}^v \ell^v(Y_{ij}^v, W_{ij}^v).$$

• We define the oracle as:

$$\overset{\star}{\mathcal{M}} = (\overset{\star}{\mathcal{M}}{}^1, \dots, \overset{\star}{\mathcal{M}}{}^V) = \operatorname*{argmin}_{\|\mathcal{W}\|_{\infty} \leq \gamma} R(\mathcal{W}),$$

where $R(\mathcal{W}) = \mathbb{E}[R_{\mathcal{Y}}(\mathcal{W})].$

 For a tuning parameter Λ > 0, the nuclear norm penalized estimator *M* is defined as

$$\widehat{\boldsymbol{\mathcal{M}}} \in \operatorname*{argmin}_{\|\boldsymbol{\mathcal{W}}\|_{\infty} \leq \gamma} \big\{ R_{\boldsymbol{\mathcal{Y}}}(\boldsymbol{\mathcal{W}}) + \Lambda \|\boldsymbol{\mathcal{W}}\|_* \big\}.$$



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Distribution-free setting: theoretical guarantee

• We denote by
$$\|\mathcal{W}\|_{\Pi,F}^2 = \sum_{\nu} \sum_{(i,j)} \pi_{ij}^{\nu} (\mathcal{W}_{ij}^{\nu})^2$$
.

Assumption 4: Assume that for every \mathcal{W} with $\|\mathcal{W}\|_{\infty} \leq \gamma$, one has $R(\mathcal{W}) - R(\overset{\star}{\mathcal{M}}) \gtrsim \frac{1}{d_u D} \|\mathcal{W} - \overset{\star}{\mathcal{M}}\|_{\Pi,F}^2$.

• Assumption 4 is called "Bernstein" condition (Mendelson, 2008; Bartlett et al., 2004; Alquier et al., 2017; Elsener and van de Geer, 2018).

Theorem [A. Klopp 2018]

Let Assumptions 1, 3, and 4 hold and $\Lambda \approx (\sqrt{\mu} + \sqrt{\log(d_u \vee D)})/(d_u D)$. Then, with probability , one has

$$R(\widehat{\mathcal{M}}) - R(\overset{\star}{\mathcal{M}}) \lesssim rac{\mu + \log(d_u \lor D)}{pd_\mu D}$$

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Toy example using CVXPY package

 V	d_u d_1 d_2		d ₃	$M^1(rank=5)$		M ² ($M^2(rank=10)$		$M^3(rank = 15)$	
3	500	0 100 200		300	$\mathcal{N}(-2, 0.5)$		Л	$\mathcal{N}(1, 0.5)$		$\mathcal{N}(2,0.5)$
				M^1	M ² M ³		л	\mathcal{M} \mathcal{M}_{col}		-
	_	% observations		10%	20%	30%	23.2	23.29% 18.69%		
	_									-
			СМС	SNN	Cold-S	tart	$\widehat{M^1}$	$\widehat{M^2}$	$\widehat{M^3}$	_
	R	MSE	0.223	0.224	0.220		0.198	0.194	0.311	L





 $\begin{array}{l} \mathsf{observed} \,+\, \mathsf{fitted} \,\, \mathsf{collective} \\ \mathsf{matrix}. \end{array}$

observed + fitted cold collective matrix.

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CVXPY [Diamond and S. Boyd (2016)]

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Collective Matrix Completion

- First theoretical guarantees on the case of noisy collective MC.
- Collective approach provides faster rate of convergences in the case of joint low-rank structure.
- Exact minimax optimal rate of convergence for 1-bit matrix completion which was known upto a logarithmic factor.
- On going work: algorithmic study with numerical experiments.

Thank you.



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