## Collective Matrix Completion

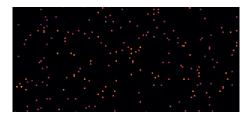
#### Mokhtar Z. Alaya Modal'X, Paris Nanterre University joint work with Olga Klopp (ESSEC Business School)





4<sup>th</sup> International Society for NonParametric Statistics Salerno, Italy, June 13<sup>th</sup> 2018

## Matrix completion is ...



- Task: given a partially observed data matrix **X**, predict the unobserved entries
- Large matrices: # rows, # columns  $\approx 10^5, 10^6$ .
- Very under-determined (often only 1-2% observed)
- Application to recommender systems, system identification, image processing, microarray data, etc.

# Motivations: recommendation systems, Netflix prize

• A popular example is the Netflix challenge (2006-2009)



- Dataset: 480K users, 18K movies, 100M ratings
- Only 1.1% of the matrix is filled!

- In general, we cannot infer missing ratings without any other information.
- This problem is under-determined, more unknown than observations.
- Low-rank assumption: fill matrix such that rank is minimum.  $\rightarrow$  A few factors explain most of the data.

Completion via rank minimization

minimize<sub>*W*</sub> rank(*W*) s. t. 
$$W_{ij} = \underbrace{X_{ij}}_{\text{observed entries}}$$
,  $(i, j) \in \underbrace{\Omega}_{\text{sampling set}}$ .

• Non-convex problem and combinatorially NP-hard!!

# Convex formulation of the rank minimization problem

$$\operatorname{rank}(\boldsymbol{X}) = \sum_{i=1}^{\min\dim(\boldsymbol{X})} \mathbb{1}_{(\sigma_i(\boldsymbol{X})>0)} = \|\sigma(\boldsymbol{X})\|_0.$$

Replace  $\ell_0$  by  $\ell_1$  [Fazel (2002), Srebro et al. (2005); Candes and Tao (2010); Recht et al. (2010); Negahban and Wainwright (2011); Klopp (2014)]:

Nuclear norm: 
$$\|\boldsymbol{X}\|_* = \sum_{i=1}^{\min\dim(\boldsymbol{X})} (\sigma_i(\boldsymbol{X})).$$

Hence temping to consider

Nuclear norm minimization:

minimize
$$_{oldsymbol{W}} \| oldsymbol{W} \|_*$$
 s. t.  $W_{ij} =$ 

$$X_{ij}$$
 ,  $(i,j) \in$ 

$$\Omega$$

observed entries

sampling set

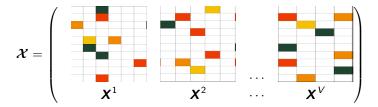
This is a convex problem !

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# Collective matrix completion: motivations

Data is often obtained from a collection of matrices
 \$\mathcal{X} = (\mathcal{X}^1, \dots, \mathcal{X}^V)\$.



- It may be beneficial to leverage all the available user data by various sources.
- **Cold-Start** problem: in recommender systems, when a new user has no rating it is impossible to predict his ratings.
- Shared structure among the sources can be useful to get better predictions.

### Collective matrix completion: model setup

- Each source view  $\boldsymbol{X}^{v} \in \mathbb{R}^{d_{u} \times d_{v}}$  and  $D = \sum_{v=1}^{V} d_{v}$ .
- We assume that the distribution of for each source X<sup>v</sup> depends on the matrix of parameters M<sup>v</sup>.
- Model: let B<sup>ν</sup><sub>ij</sub> be independent Bernoulli random variables and independent from X<sup>ν</sup><sub>ii</sub>, with parameter π<sup>ν</sup><sub>ii</sub>.

$$Y_{ij}^{\nu}=B_{ij}^{\nu}X_{ij}^{\nu}.$$

- We can think of the  $B_{ii}^{v}$  as masked variables.
- $\pi_{ij}^{v}$  = probability to observe the (i, j)-th entry of the *v*-th source.

# Collective matrix completion: sampling scheme

• We consider general sampling model where we only assume:

**Assumption 1:** There exists a positive constant  $0 s.t. <math>\min_{v \in [V]} \min_{(i,j) \in [d_u] \times [d_v]} \pi_{ij}^v \ge p$ .

#### [Klopp (2015); Klopp et al. (2015)]

- $\pi_{i}^{v} = \sum_{j=1}^{d_{v}} \pi_{ij}^{v}$  the probability to observe an element from the *i*-th row of  $\mathbf{X}^{v}$ .
- $\pi_{\bullet j}^{v} = \sum_{i=1}^{d_u} \pi_{ij}^{v}$  the probability to observe an element from the *j*-th column of  $\mathbf{X}^{v}$ .

$$\max_{v\in[V]}\max_{(i,j)\in[d_u]\times[d_v]}(\pi_{i\bullet}^v,\pi_{\bullet j}^v)\leq\mu.$$

### Exponential family noise

- Heterogeneous sources: (ratings), (counting: number of clicks) (binomial: like/dislike)
- General framework: natural exponential family:

 $X_{ij}^{v}|M_{ij}^{v} \sim h^{v}(X_{ij}^{v})\exp\left(X_{ij}^{v}M_{ij}^{v}-G^{v}(M_{ij}^{v})
ight).$ 

[Gunasekar et al. (2014); Cao and Xie (2016); Lafond (2015)]

• Many distributions belong to the exponential family: Gaussian, binomial, Poisson, exponential, etc.

**Assumption 2:** - The distribution of  $X_{ij}^{\nu}$  has sub-exponential tail. - Strong convexity of the log-partition function  $G^{\nu}$ .

## Exponential family noise: estimation procedure

• Given observations  $\mathcal{Y} = (\mathcal{Y}^1, \dots, \mathcal{Y}^V)$ , we write the negative log-likelihood as

$$\mathscr{L}_{\mathcal{Y}}(\mathcal{W}) = -\frac{1}{d_u D} \sum_{v \in [V]} \sum_{(i,j) \in [d_u] \times [d_v]} B_{ij}^v (Y_{ij}^v W_{ij}^v - G^v (W_{ij}^v)).$$

• The nuclear norm penalized estimator  $\widehat{\mathcal{M}}$  of  $\boldsymbol{\mathcal{M}}$  is defined as follows:

$$\widehat{\boldsymbol{\mathcal{M}}} = (\widehat{\boldsymbol{\boldsymbol{\mathcal{M}}}}^1, \dots, \widehat{\boldsymbol{\boldsymbol{\mathcal{M}}}}^V) = \operatorname*{argmin}_{\|\boldsymbol{\mathcal{W}}\|_{\infty} \leq \gamma} \mathscr{L}_{\boldsymbol{\mathcal{Y}}}(\boldsymbol{\mathcal{W}}) + \lambda \|\boldsymbol{\mathcal{W}}\|_*,$$

 λ > 0 is a positive regularization parameter that balances the trade-off between model fit and privileging a low-rank solution. Upper bound of Frobenius estimation risk norm: the rate of convergence has the following dominant term:

#### Theorem [A., Klopp 2018]

Assume that Assumptions 1 and 2 hold and

$$\lambda pprox rac{\sqrt{\mu} + (\log(d_u \lor D))^{3/2}}{d_u D}.$$

Then, with high probability, one has

$$\frac{1}{d_u D} \|\widehat{\boldsymbol{\mathcal{M}}} - \boldsymbol{\mathcal{M}}\|_F^2 \lesssim \frac{\mathsf{rank}(\boldsymbol{\mathcal{M}})(\mu + (\log(d_u \vee D))^{3/2})}{p^2 d_u D}$$

#### Exponential family noise: theoretical guarantee

• Uniform sampling: If  $c_1/(d_u d_v) \le \pi_{ij}^v \le c_2/(d_u d_v)$ , then

$$rac{1}{d_u D} \| \widehat{\mathcal{M}} - \mathcal{M} \|_F^2 \lesssim rac{\mathrm{rank}(\mathcal{M})}{p(d_u \wedge D)}.$$

- We denote n = ∑<sub>ν∈[V]</sub> ∑<sub>(i,j)∈[d<sub>u</sub>]×[d<sub>v</sub>]</sub> π<sup>v</sup><sub>ij</sub>, the expected number of observations.
- Sample complexity:

 $n \gtrsim \operatorname{rank}(\mathcal{M})(d_u \lor D).$ 

# Example: 1-bit matrix completion

- 1-bit matrix completion: 𝒱 ∈ {+1, -1} with probability f(𝓜) for some link-function f [ Davenport et al. (2014); Klopp et al. (2015); Alquier et al. (2017)]
- Klopp et al. (2015) obtained the rate rank(M)(d<sub>u</sub> ∨ D) log(d<sub>u</sub> ∨ D)/n as the upper bound and rank(M)(d<sub>u</sub> ∨ D)/n as the lower bound for 1-bit matrix completion.

Corollary[A., Klopp 2018]

$$\frac{1}{d_u D} \|\widehat{\boldsymbol{\mathcal{M}}} - \boldsymbol{\mathcal{M}}\|_F^2 \lesssim \frac{\mathrm{rank}(\boldsymbol{\mathcal{M}})(d_u \vee D)}{n}$$

• **Answer** the important theoretical question: what is the exact minimax rate of convergence for 1-bit matrix completion which was previously known up to a logarithmic factor.

- We do not assume any specific model for the observations.
- We consider the risk of estimating  $X^{\nu}$  with a loss function  $\ell^{\nu}$ ,
- We focus on non-negative loss functions that are Lipschitz:

**Assumption 3:** We assume that the loss function  $\ell^{v}(y, \cdot)$  is  $\rho_{v}$ -Lipschitz in its second argument:  $\ell^{v}(y, x) - \ell^{v}(y, x')| \leq \rho_{v}|x - x'|.$ 

Examples: hinge loss with ℓ<sup>v</sup>(y, y') = max(0, 1 - yy'), logistic loss with ℓ<sup>v</sup>(y, y') = log(1 + exp(-yy')), etc.

# Distribution-free setting: estimation procedure

• Goodness-of-fit term:

$$R_{\mathcal{Y}}(\mathcal{W}) = \frac{1}{d_u D} \sum_{v \in [V]} \sum_{(i,j) \in [d_u] \times [d_v]} B_{ij}^v \ell^v(Y_{ij}^v, W_{ij}^v).$$

• We define the oracle as:

$$\overset{\star}{\mathcal{M}} = (\overset{\star}{\mathcal{M}}{}^1, \dots, \overset{\star}{\mathcal{M}}{}^V) = \operatorname*{argmin}_{\|\mathcal{W}\|_{\infty} \leq \gamma} R(\mathcal{W}),$$

where  $R(\mathcal{W}) = \mathbb{E}[R_{\mathcal{Y}}(\mathcal{W})].$ 

 For a tuning parameter Λ > 0, the nuclear norm penalized estimator *M* is defined as

$$\widehat{\boldsymbol{\mathcal{M}}} \in \operatorname*{argmin}_{\|\boldsymbol{\mathcal{W}}\|_{\infty} \leq \gamma} \big\{ R_{\boldsymbol{\mathcal{Y}}}(\boldsymbol{\mathcal{W}}) + \Lambda \|\boldsymbol{\mathcal{W}}\|_* \big\}.$$

## Distribution-free setting: theoretical guarantee

• We denote by 
$$\|\boldsymbol{\mathcal{W}}\|_{\Pi,F}^2 = \sum_{\nu} \sum_{(i,j)} \pi_{ij}^{\nu} (W_{ij}^{\nu})^2$$
.

Assumption 4: Assume that for every  $\mathcal{W}$  with  $\|\mathcal{W}\|_{\infty} \leq \gamma$ , one has  $R(\mathcal{W}) - R(\overset{\star}{\mathcal{M}}) \gtrsim \frac{1}{d_u D} \|\mathcal{W} - \overset{\star}{\mathcal{M}}\|_{\Pi,F}^2$ .

• Assumption 4 is called "Bernstein" condition (Mendelson, 2008; Bartlett et al., 2004; Alquier et al., 2017; Elsener and van de Geer, 2018).

#### Theorem [A. Klopp 2018]

Let Assumptions 1, 3, and 4 hold and  $\Lambda \approx (\sqrt{\mu} + \sqrt{\log(d_u \vee D)})/(d_u D)$ . Then, with probability , one has

$$R(\widehat{\boldsymbol{\mathcal{M}}}) - R(\overset{\star}{\boldsymbol{\mathcal{M}}}) \lesssim rac{\mu + \log(d_u \vee D)}{pd_u D}$$

- First theoretical guarantees on the case of noisy collective MC.
- Collective approach provides faster rate of convergences in the case of joint low-rank structure.
- Exact minimax optimal rate of convergence for 1-bit matrix completion which was known upto a logarithmic factor.
- On going work: algorithmic study with numerical experiments.



# Toy Illustration using cvxpy package

V	du	$d_1$ $d_2$ $d$		d <sub>3</sub>	$M^1(rank=5)$		M <sup>2</sup> (	$M^2(rank=10)$		$d^3(rank=15)$
3	500	100	200	300	$\mathcal{N}(-2, 0.5)$		Л	$\mathcal{N}(1, 0.5)$		$\mathcal{N}(2, 0.5)$
	_			$M^1$	$M^2$	M <sup>3</sup>	л	1 )	$M_{cold}$	-
		% observations		10%	20%	30%	23.2	23.29% 18.69		_
										-
			СМС	SNN	Cold-S	tart	$\widehat{M^1}$	$\widehat{M^2}$	$\widehat{M^3}$	
	R	MSE	0.223	0.224	0.220		0.198	0.194	0.31	1





 $\begin{array}{l} {\sf observed} \ + \ {\sf fitted} \ {\sf collective} \\ {\sf matrix}. \end{array}$ 

 $\begin{array}{l} \text{observed} \ + \ \text{fitted} \ \text{cold} \ \text{collective} \\ \text{matrix}. \end{array}$ 

#### cvxpy [Diamond and S. Boyd (2016)]

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